

Name:

Honor Code:

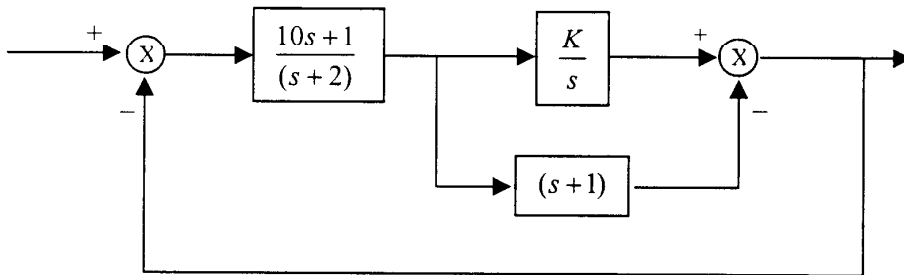
KEY - D

Instructions:

- Use the space on the accompanying pages to work the problems. Do not use a bluebook. Attach additional worksheets if necessary.
- If you wish to have partial credit awarded for any of your incorrect answers **you must write clearly and legibly**. Explain your work in words, if necessary.
- Read the instructions provided with each problem.
- Don't Panic.

1.

- (a) [16 points] Find the range of K for stability in the following system
 (b) [2 points] *Roughly* sketch the step response for K=-100 [use your results from (a) as a guide].
 (c) [2 points] *Roughly* sketch the step response for K=+100 [use your results from (a) as a guide].



Parallel $\frac{K}{s} - (s+1) = \frac{K - s^2 - s}{s}$

Cascade $\frac{10s+1}{s+2} \cdot \frac{K - s^2 - s}{s} = \frac{(10s+1)(K - s^2 - s)}{s(s+2)}$

Feedback $\frac{(10s+1)(K - s^2 - s)}{s(s+2) + (10s+1)(K - s^2 - s)}$

$$= \frac{(10s+1)(K-s^2-2)}{s^2+2s+(10Ks-10s^3-10s^2+K-s^2-2)}$$

$$= \frac{(10s+1)(K-s^2-2)}{s^3[-10]+s^2[-10]+s[10K+1]+K}$$

R-H table

$$s^3 \quad -10$$

$$s^2 \quad -10$$

$$10K+1$$

$$K$$

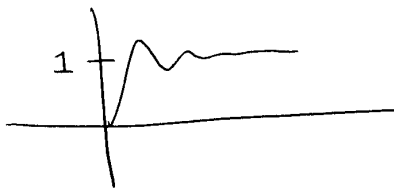
$$s^1 \quad 9K+1$$

$$s^0 \quad K$$

For stability $9K+1 < 0$ $K < -1/9$

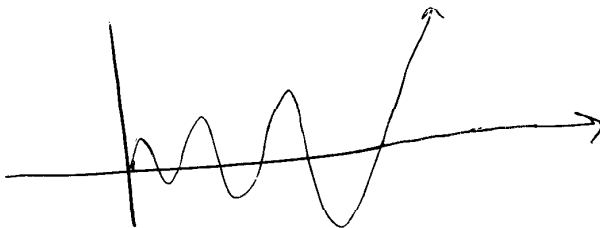
$K < 0$

b) stable



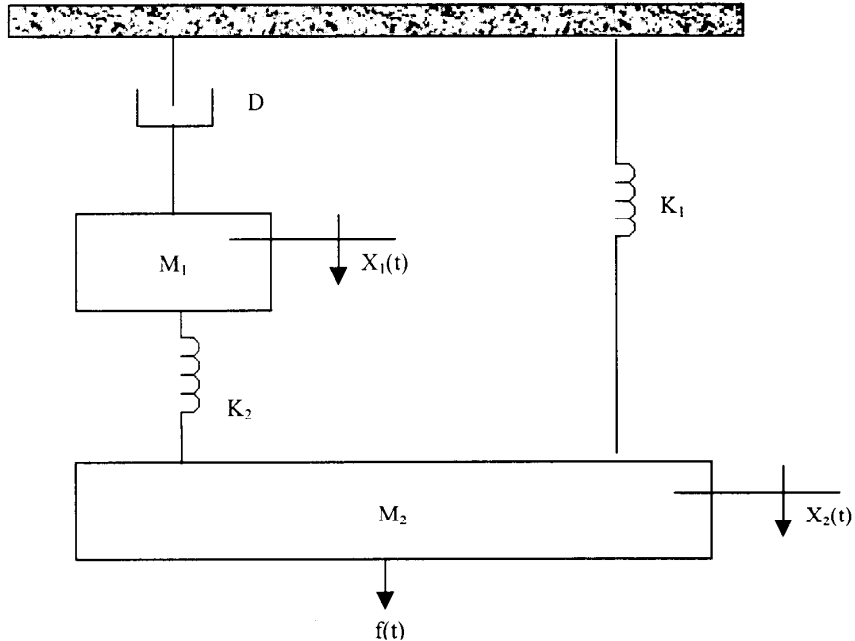
FV = 1 Via Final Value theorem

c) Unstable



2.

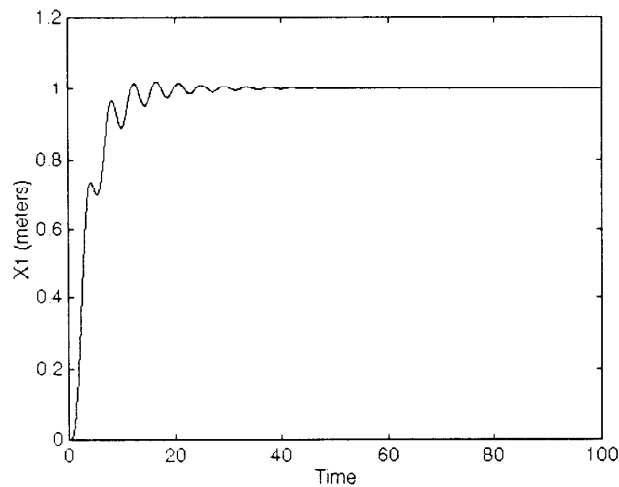
(a) [15 points] Find the Transfer Function $X_1(s)/F(s)$



(b) [2 points] Let $M_1=M_2=1$, $K_1=K_2=1$, and $D=2$. Use the initial value theorem to show that when excited by a step input, $x_1(t) \rightarrow 0$ as $t \rightarrow 0$.

(c) [2 points] Use the final value theorem to show that $x_1(t) \rightarrow 1$ as $t \rightarrow \infty$ when $f(t)=u(t)$.

(d) [6 points] The following graph shows the step response of the system. Explain why it looks the way it does in two or three sentences.



(a)

FBD:

$$\boxed{m_1} \quad \uparrow M_1 \omega^2 x_1(\omega) \quad \uparrow D \omega x_1(\omega) \quad \uparrow K_2 (x_1(\omega) - x_2(\omega))$$

$$(1) \quad x_1(\omega) [M_1 \omega^2 + D \omega + K_2] + x_2(\omega) [-K_2] = 0$$

$$F(\omega) \downarrow \quad \boxed{m_2} \quad \uparrow M_2 \omega^2 x_2(\omega) \quad \uparrow K_1 x_2(\omega) \quad \uparrow K_2 (x_2(\omega) - x_1(\omega))$$

$$(2) \quad F(\omega) = x_1(\omega) [-K_2] + x_2(\omega) [M_2 \omega^2 + K_1 + K_2]$$

$$\text{From (1)} \quad x_2(\omega) = x_1(\omega) \left[\frac{M_1 \omega^2 + D \omega + K_2}{K_2} \right]$$

$$\Rightarrow F(\omega) = x_1(\omega) \left[-K_2 \right] + \left[\frac{M_1 \omega^2 + D \omega + K_2}{K_2} \right] [M_2 \omega^2 + K_1 + K_2]$$

$$\frac{x_1(\omega)}{F(\omega)} = \frac{1}{-K_2 + \frac{(M_1 \omega^2 + D \omega + K_2)}{K_2} (M_2 \omega^2 + K_1 + K_2)}$$

$$= \frac{K_2}{(M_1 \omega^2 + D \omega + K_2)(M_2 \omega^2 + K_1 + K_2) - K_2^2}$$

$$(c) \quad \lim_{\omega \rightarrow 0} \omega G(\omega) = \frac{K_2}{(K_2)(K_1 + K_2) - K_2^2} = \frac{K_2}{K_1 K_2} = \underline{1}$$

$$(b) \quad \lim_{\omega \rightarrow \infty} \omega G(\omega) = \underline{0}$$

d) The force is applied starting at $t=0$. The block responds by moving down quickly. The springs and dampers then pull back causing the mass to recoil. As time goes

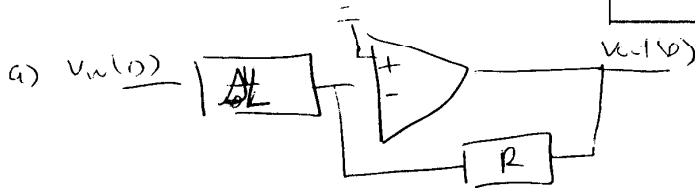
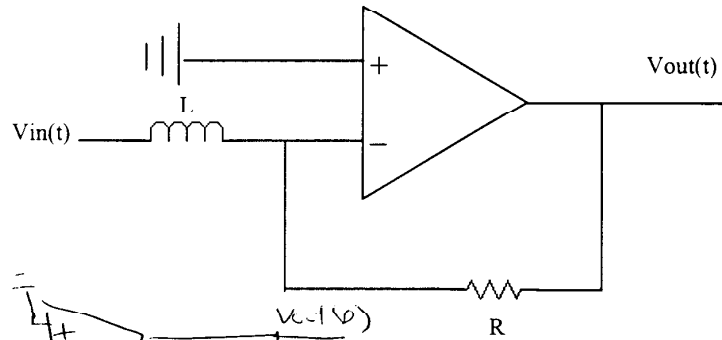
on, eventually the block settles at position = 1.

3.

(a) [5 points] Find the Transfer Function $V_{out}(s)/V_{in}(s)$ for the following system.

(b) [5 points] Determine and plot the step response.

(c) [5 points] Find $V_{out}(t)$ when $V_{in}(t) = \sin 10\pi t$.

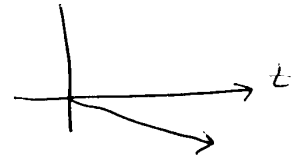


$$\frac{0 - V_{in}(s)}{sL} + \frac{0 - V_{out}(s)}{R} = 0$$

$$\boxed{\frac{V_{out}(s)}{V_{in}(s)} = -\frac{R}{sL}}$$

b)

$$\text{Output}(s) = \frac{-R}{sL} \cdot \frac{1}{s} = \frac{-R}{L} \cdot \frac{1}{s^2} = \frac{-R}{L} t u(t)$$



$$c) V_{out}(s) = \frac{-R}{sL} \cdot \frac{10\pi}{s^2 + (10\pi)^2}$$

$$= \frac{-R \cdot 10\pi / L}{(s)(s^2 + (10\pi)^2)}$$

$$= \frac{\frac{-R}{L} \frac{1}{10\pi}}{s} + \frac{K_1 s + K_2}{s^2 + (10\pi)^2}$$

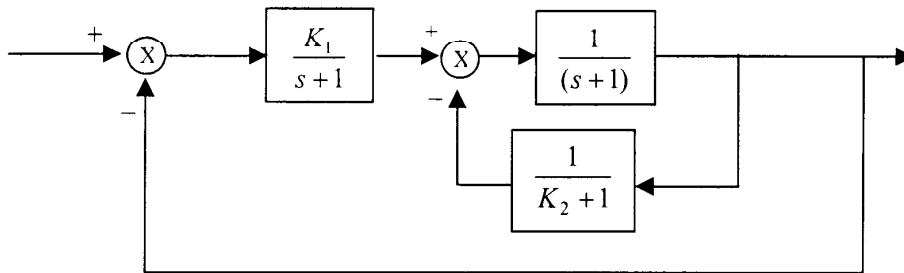
$$= \frac{\frac{-R}{L} \frac{1}{10\pi} s^2 + \frac{-R}{L} 10\pi + K_1 s^2 + K_2 s}{s(s^2 + (10\pi)^2)}$$

$$K_1 = +\frac{1}{10\pi} \cdot \frac{R}{L} \quad K_2 = 0$$

$$V_{out}(s) = \frac{-\frac{R}{L} \cdot \frac{1}{10\pi}}{s} + \frac{\frac{+R}{L \cdot 10\pi} s}{s^2 + (10\pi)^2}$$

$$V_{out}(t) = \left(-\frac{R}{L} \cdot \frac{1}{10\pi} + \frac{R}{L \cdot 10\pi} \cos 10\pi t \right) u(t)$$

5. Consider the following system



- (a) [8 points] Write the Closed Loop Transfer Function.
- (b) [6 points] Find all relevant second-order parameters of the system when $K_1=1$ and $K_2=2$ and sketch the output when the system is excited by a step input. Show that the system is stable.
- (c) [6 points] Repeat (b) for $K_1=2$ and $K_2=1$. Show that the system is stable.

(a)

$$\frac{\text{FEEDBACK}}{\text{Series}} = \frac{\frac{1}{D+1}}{1 + \left(\frac{1}{D+1}\right)\left(\frac{1}{K_2+1}\right)} \times \frac{(D+1)(K_2+1)}{(D+1)(K_2+1)}$$

$$= \frac{K_2+1}{(D+1)(K_2+1)+1} = \frac{K_2+1}{K_2 D + D + K_2 + 2}$$

$$\left(\frac{K_1}{D+1}\right) \left(\frac{K_2+1}{D(K_2+1) + (K_2+2)}\right) = \frac{K_1(K_2+1)}{D^2[K_2+1] + D[2K_2+3] + [K_2+2]}$$

$$\frac{\text{Feedback}}{\text{Series}} = \frac{K_1(K_2+1)}{D^2[K_2+1] + D[2K_2+3] + [K_1 K_2 + K_1 + K_2 + 2]}$$

$$b) \quad TF = \frac{3}{3s^2 + 7s + 7} = \frac{1}{s^2 + \frac{7}{3}s + \frac{7}{3}}$$

$$\omega_n^2 = \frac{7}{3}, \quad 2\zeta\omega_n = \frac{7}{3}$$

$$\Rightarrow \boxed{OS = 2.437\% \quad T_s = 3.43s \quad T_p = 3.19}$$

stability

s^2	3	7
s^1	7	
s^0	7	

or

s^2	1	$7/3$
s^1	$7/3$	
s^0	$7/3$	

$$c) \quad TF = \frac{4}{2s^2 + 5s + 7} = \frac{2}{s^2 + \frac{5}{2}s + \frac{7}{2}}$$

$$\omega_n^2 = \frac{7}{2}, \quad 2\zeta\omega_n = \frac{5}{2}$$

$$\Rightarrow \boxed{OS = 5.45\% \quad T_s = 3.2s \quad T_p = 2.3s}$$

stability

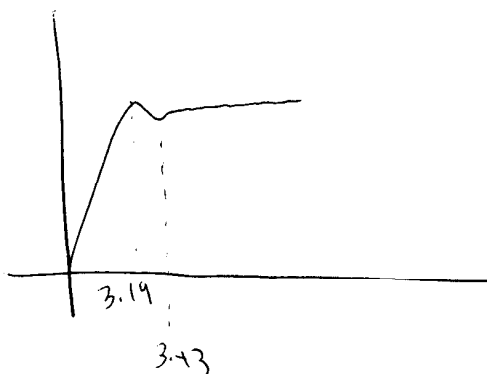
s^2	2	7
s^1	5	
s^0	7	

or

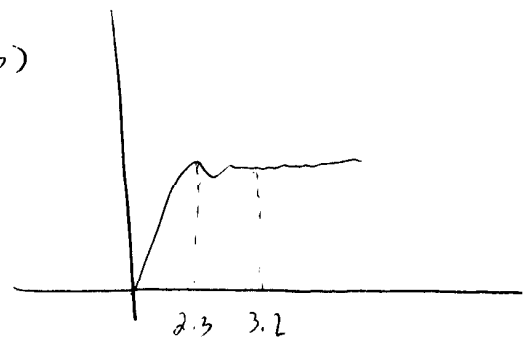
s^2	1	$7/2$
s^1	$5/2$	
s^0	$7/2$	

graphs:

(a)



(b)



5. [20 points] Answer the following 10 questions True or False.

Answer true if and only if the system is stable for each of the closed loop denominators.

- T i) Denominator(s) = $s^2 + 3s + 2$
F ii) Denominator(s) = $(s-1)(-s^3 + 4s^2 - 2s + 1)$
T iii) Denominator(s) = $(s+1)(s+2)(s^2 + 4s + 3)$
F iv) Denominator(s) = $(s+1)(s+2)(s^2 - 4s + 3)$

Answer the following second order systems questions true or false

- F v) A CLTF with denominator $s^2 + 3s + 2$ is underdamped
T vi) It is possible to choose K in to get 10% overshoot in a system with CLTF $s^2 + 3s + K$.

Answer the following partial fraction expansion questions true or false

T vii)

$$\frac{(s+1)}{s^2(s+2)} = \frac{.25}{s} + \frac{.5}{s^2} + \frac{-.25}{s+2}$$

F viii)

$$\frac{(s+1)}{s(s+2)} = \frac{.25}{s} + \frac{-.25}{s+2}$$

F ix)

$$\frac{(s+1)}{s(s^2 + 2s + 2)} = \frac{1}{s} + \frac{-1}{s+1}$$

- T x) The inverse Laplace Transform of

$$\frac{(s+1)}{s(s^2 + 2s + 2)}$$

Includes an $e^{-at} \sin(\omega t)$ term for some ω and a .